

# NAG Toolbox for MATLAB

## f08xb

### 1 Purpose

f08xb computes the generalized eigenvalues, the generalized real Schur form  $(S, T)$  and, optionally, the left and/or right generalized Schur vectors for a pair of  $n$  by  $n$  real nonsymmetric matrices  $(A, B)$ .

Estimates of condition numbers for selected generalized eigenvalue clusters and Schur vectors are also computed.

### 2 Syntax

```
[a, b, sdim, alphas, alphas, beta, vsr, rconde, rcondv, info] =  
f08xb(jobvsl, jobvsr, sort, selctg, sense, a, b, 'n', n)
```

### 3 Description

The generalized real Schur factorization of  $(A, B)$  is given by

$$A = QSZ^T, \quad B = QTZ^T,$$

where  $Q$  and  $Z$  are orthogonal,  $T$  is upper triangular and  $S$  is upper quasi-triangular with 1 by 1 and 2 by 2 diagonal blocks. The generalized eigenvalues,  $\lambda$ , of  $(A, B)$  are computed from the diagonals of  $S$  and  $T$  and satisfy

$$Az = \lambda Bz,$$

where  $z$  is the corresponding generalized eigenvector.  $\lambda$  is actually returned as the pair  $(\alpha, \beta)$  such that

$$\lambda = \alpha/\beta$$

since  $\beta$ , or even both  $\alpha$  and  $\beta$  can be zero. The columns of  $Q$  and  $Z$  are the left and right generalized Schur vectors of  $(A, B)$ .

Optionally, f08xb can order the generalized eigenvalues on the diagonals of  $(S, T)$  so that selected eigenvalues are at the top left. The leading columns of  $Q$  and  $Z$  then form an orthonormal basis for the corresponding eigenspaces, the deflating subspaces.

f08xb computes  $T$  to have nonnegative diagonal elements, and the 2 by 2 blocks of  $S$  correspond to complex conjugate pairs of generalized eigenvalues. The generalized Schur factorization, before reordering, is computed by the  $QZ$  algorithm.

The reciprocals of the condition estimates, the reciprocal values of the left and right projection norms, are returned in **rconde**(1) and **rconde**(2) respectively, for the selected generalized eigenvalues, together with reciprocal condition estimates for the corresponding left and right deflating subspaces, in **rcondv**(1) and **rcondv**(2). See Section 4.11 of Anderson *et al.* 1999 for further information.

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D 1999 *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F 1996 *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

## 5 Parameters

### 5.1 Compulsory Input Parameters

1: **jobvsl – string**

If **jobvsl** = 'N', do not compute the left Schur vectors.

If **jobvsl** = 'V', compute the left Schur vectors.

*Constraint:* **jobvsl** = 'N' or 'V'.

2: **jobvsr – string**

If **jobvsr** = 'N', do not compute the right Schur vectors.

If **jobvsr** = 'V', compute the right Schur vectors.

*Constraint:* **jobvsr** = 'N' or 'V'.

3: **sort – string**

Specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form.

**sort** = 'N'

Eigenvalues are not ordered.

**sort** = 'S'

Eigenvalues are ordered (see user-supplied logical function **selctg**).

*Constraint:* **sort** = 'N' or 'S'.

4: **selctg – string containing name of m-file**

If **sort** = 'S', **selctg** is used to select generalized eigenvalues to the top left of the generalized Schur form.

If **sort** = 'N', **selctg** is not referenced and f08xb may be called with the string 'f08xaz'.

Its specification is:

```
[result] = selctg(ar, ai, b)
```

#### Input Parameters

1: **ar – double scalar**

2: **ai – double scalar**

3: **b – double scalar**

An eigenvalue  $(\mathbf{ar}(j) + \sqrt{-1} \times \mathbf{ai}(j)) / \mathbf{b}(j)$  is selected if **selctg**(**ar**(*j*), **ai**(*j*), **b**(*j*)) is **true**.

If either one of a complex conjugate pair is selected, then both complex generalized eigenvalues are selected.

Note that in the ill-conditioned case, a selected complex generalized eigenvalue may no longer satisfy **selctg**(**ar**(*j*), **ai**(*j*), **b**(*j*)) = **true** after ordering. **ifail** = Np2 in this case.

#### Output Parameters

1: **result – logical scalar**

The result of the function.

5: **sense – string**

Determines which reciprocal condition numbers are computed.

**sense** = 'N'

None are computed.

**sense** = 'E'

Computed for average of selected eigenvalues only.

**sense** = 'V'

Computed for selected deflating subspaces only.

**sense** = 'B'

Computed for both.

If **sense** = 'E', 'V' or 'B', **sort** must equal 'S'.

*Constraint:* **sense** = 'N', 'E', 'V' or 'B'.

6: **a(lda,\*)** – **double array**

The first dimension of the array **a** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

The first of the pair of matrices,  $A$ .

7: **b(ldb,\*)** – **double array**

The first dimension of the array **b** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

The second of the pair of matrices,  $B$ .

## 5.2 Optional Input Parameters

1: **n** – **int32 scalar**

*Default:* The first dimension of the arrays **a**, **b** and the second dimension of the arrays **a**, **b**. (An error is raised if these dimensions are not equal.)

$n$ , the order of the matrices  $A$  and  $B$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

## 5.3 Input Parameters Omitted from the MATLAB Interface

lda, ldb, ldvsl, ldvsr, work, lwork, iwork, liwork, bwork

## 5.4 Output Parameters

1: **a(lda,\*)** – **double array**

The first dimension of the array **a** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

**a** has been overwritten by its generalized Schur form  $S$ .

2: **b(ldb,\*)** – **double array**

The first dimension of the array **b** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

**b** has been overwritten by its generalized Schur form  $T$ .

3: **sdim** – int32 scalar

If **sort** = 'N', **sdim** = 0.

If **sort** = 'S', **sdim** = number of eigenvalues (after sorting) for which user-supplied logical function **selectg** is **true**. (Complex conjugate pairs for which **selectg** is **true** for either eigenvalue count as 2.)

4: **alphar**(\*) – double array

**Note:** the dimension of the array **alphar** must be at least  $\max(1, \mathbf{n})$ .

See the description of **beta**.

5: **alphai**(\*) – double array

**Note:** the dimension of the array **alphai** must be at least  $\max(1, \mathbf{n})$ .

See the description of **beta**.

6: **beta**(\*) – double array

**Note:** the dimension of the array **beta** must be at least  $\max(1, \mathbf{n})$ .

$(\mathbf{alphar}(j) + \mathbf{alphai}(j) \times i) / \mathbf{beta}(j)$ , for  $j = 1, \dots, \mathbf{n}$ , will be the generalized eigenvalues.  $\mathbf{alphar}(j) + \mathbf{alphai}(j) \times i$ , and  $\mathbf{beta}(j)$ , for  $j = 1, \dots, \mathbf{n}$ , are the diagonals of the complex Schur form  $(S, T)$  that would result if the 2 by 2 diagonal blocks of the real Schur form of  $(A, B)$  were further reduced to triangular form using 2 by 2 complex unitary transformations.

If  $\mathbf{alphai}(j)$  is zero, then the  $j$ th eigenvalue is real; if positive, then the  $j$ th and  $(j + 1)$ st eigenvalues are a complex conjugate pair, with  $\mathbf{alphai}(j + 1)$  negative.

**Note:** the quotients  $\mathbf{alphar}(j) / \mathbf{beta}(j)$  and  $\mathbf{alphai}(j) / \mathbf{beta}(j)$  may easily overflow or underflow, and  $\mathbf{beta}(j)$  may even be zero. Thus, you should avoid naively computing the ratio  $\alpha / \beta$ . However, **alphar** and **alphai** will always be less than and usually comparable with  $\|\mathbf{a}\|_2$  in magnitude, and **beta** will always be less than and usually comparable with  $\|\mathbf{b}\|_2$ .

7: **vsl**(ldvsl,\*) – double array

The first dimension, **ldvsl**, of the array **vsl** must satisfy

if **jobvsl** = 'V',  $\mathbf{ldvsl} \geq \max(1, \mathbf{n})$ ;  
 $\mathbf{ldvsl} \geq 1$  otherwise.

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

If **jobvsl** = 'V', **vsl** will contain the left Schur vectors,  $Q$ .

If **jobvsl** = 'N', **vsl** is not referenced.

8: **vsr**(ldvsr,\*) – double array

The first dimension, **ldvsr**, of the array **vsr** must satisfy

if **jobvsr** = 'V',  $\mathbf{ldvsr} \geq \max(1, \mathbf{n})$ ;  
 $\mathbf{ldvsr} \geq 1$  otherwise.

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

If **jobvsr** = 'V', **vsr** will contain the right Schur vectors,  $Z$ .

If **jobvsr** = 'N', **vsr** is not referenced.

9: **rconde**(2) – double array

If **sense** = 'E' or 'B', **rconde**(1) and **rconde**(2) contain the reciprocal condition numbers for the average of the selected eigenvalues.

If **sense** = 'N' or 'V', **rconde** is not referenced.

10: **rcondv(2) – double array**

If **sense** = 'V' or 'B', **rcondv(1)** and **rcondv(2)** contain the reciprocal condition numbers for the selected deflating subspaces.

if **sense** = 'N' or 'E', **rcondv** is not referenced.

11: **info – int32 scalar**

**info** = 0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**info** =  $-i$

If **info** =  $-i$ , parameter  $i$  had an illegal value on entry. The parameters are numbered as follows:

1: **jobvsl**, 2: **jobvsr**, 3: **sort**, 4: **selectg**, 5: **sense**, 6: **n**, 7: **a**, 8: **lda**, 9: **b**, 10: **ldb**, 11: **sdim**, 12: **alphar**, 13: **alphai**, 14: **beta**, 15: **vsl**, 16: **ldvsl**, 17: **vsr**, 18: **ldvsr**, 19: **rconde**, 20: **rcondv**, 21: **work**, 22: **lwork**, 23: **iwork**, 24: **liwork**, 25: **bwork**, 26: **info**.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

**info** = 1 to  $N$

The  $QZ$  iteration failed.  $(A, B)$  are not in Schur form, but **alphar**( $j$ ), **alphai**( $j$ ), and **beta**( $j$ ) should be correct for  $j = \mathbf{info} + 1, \dots, \mathbf{n}$ .

**info** =  $N + 1$

Unexpected error returned from f08xe.

**info** =  $N + 2$

After reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the generalized Schur form no longer satisfy **selectg** = **true**. This could also be caused by underflow due to scaling.

**info** =  $N + 3$

The eigenvalues could not be reordered because some eigenvalues were too close to separate (the problem is very ill-conditioned).

## 7 Accuracy

The computed generalized Schur factorization satisfies

$$A + E = QSZ^T, \quad B + F = QTZ^T,$$

where

$$\|(E, F)\|_F = O(\epsilon)\|(A, B)\|_F$$

and  $\epsilon$  is the *machine precision*. See Section 4.11 of Anderson *et al.* 1999 for further details.

## 8 Further Comments

The total number of floating-point operations is proportional to  $n^3$ .

The complex analogue of this function is f08xp.

## 9 Example

f08xb\_selctg.m

```
function [result] = selctg(ar, ai, b)
    if (ai == 0)
        result = true;
    else
        result = false;
    end
```

```
jobvsl = 'Vectors (left)';
jobvsr = 'Vectors (right)';
sort = 'Sort';
sense = 'Both reciprocal condition numbers';
a = [3.9, 12.5, -34.5, -0.5;
     4.3, 21.5, -47.5, 7.5;
     4.3, 21.5, -43.5, 3.5;
     4.4, 26, -46, 6];
b = [1, 2, -3, 1;
     1, 3, -5, 4;
     1, 3, -4, 3;
     1, 3, -4, 4];
[aOut, bOut, sdim, alphas, alphai, beta, vsl, vsr, rconde, rcondv, info]
= ...
    f08xb(jobvsl, jobvsr, sort, 'f08xb_selctg', sense, a, b)
```

```
aOut =
    3.8009   -69.4505    50.3135   -43.2884
         0     9.2033   -0.2001     5.9881
         0         0     1.4279     4.4453
         0         0     0.9019    -1.1962

bOut =
    1.9005   -10.2285     0.8658   -5.2134
         0     2.3008     0.7915     0.4262
         0         0     0.8101         0
         0         0         0    -0.2823

sdim =
         2

alphas =
    3.8009
    9.2033
    0.8571
    0.8571
alphai =
         0
         0
    1.1429
   -1.1429
beta =
    1.9005
    2.3008
    0.2857
    0.2857
vsl =
    0.4642    0.7886    0.2915   -0.2786
    0.5002   -0.5986    0.5638   -0.2713
    0.5002    0.0154   -0.0107    0.8657
    0.5331   -0.1395   -0.7727   -0.3151
vsr =
    0.9961   -0.0014    0.0887   -0.0026
    0.0057   -0.0404   -0.0938   -0.9948
    0.0626    0.7194   -0.6908    0.0363
    0.0626   -0.6934   -0.7114    0.0956
rconde =
    0.1896
```

```
      0.0183
rcondv =
      0.0544
      0.0900
info =
          0
```

---